

Splitting methods

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Contents

Numerical Analysis

Our group

My work

Numerical Analysis

“Numerical analysis aims to construct and analyze quantitative methods for the automatic computation of approximate solutions to mathematical problems.”

— Gustaf Söderlind

“Numerical analysis is the area of mathematics and computer science that creates, analyzes, and implements algorithms for solving numerically the problems of continuous mathematics.”

— Kendall E. Atkinson

“Numerical analysis is the study of algorithms for the problems of continuous mathematics.”

— Lloyd N. Trefethen

Numerical Analysis topics

Numerical linear algebra

- Solving systems of equations

- Computing eigenvalues

- Matrix factorizations, functions of matrices

Approximation theory

- Interpolation, extrapolation

- Numerical integration

Optimization

- Min/max of real-valued functions

- Possibly with constraints

Differential equations

- ODEs, PDEs

- Integral equations

- DAEs, SDEs, DDEs

Research areas at Numerical Analysis in Lund

Main focus: Differential equations

We work with

- **Adaptivity** (Gustaf Söderlind)
- **DAEs** (Claus Führer)
- **Multistep methods** (Carmen Arévalo)
- **Integral equations** (Johan Helsing)
- **Real-time simulation** (Christian Andersson)
- **Splitting methods** (Eskil Hansen, Erik Henningsson, Tony Stillfjord)

and more

My work: Laplacian example

$$\begin{aligned}\frac{d}{dt}u(t, x) &= \Delta u(t, x), \quad x \in [0, 1], \quad t \in [0, 1] \\ u(t, 0) &= u(t, 1) = 0 \\ u(0, x) &= f(x)\end{aligned}$$

Easy and fast to solve by Fast Fourier Transform (FFT) techniques

But what about this?

$$\begin{aligned}\frac{d}{dt}u(t, x) &= \Delta u(t, x) + g(u), \quad x \in [0, 1], \quad t \in [0, 1] \\ u(t, 0) &= u(t, 1) = 0 \\ u(0, x) &= f(x)\end{aligned}$$

$g(u)$ non-linear, but “nice”, non-stiff

FFT-techniques do not work (or complicated and specific)

A typical problem

$$\begin{aligned}\frac{d}{dt}u(t) &= Au(t) + Bu(t), \quad t \in [0, 1], \\ u(0) &= \eta\end{aligned}$$

Abstract evolution equation

Space dependency and boundary conditions hidden in the operators A and B

Full problem difficult/expensive

Sub-problems $\frac{d}{dt}u(t) = Au(t)$ easy/cheap
 $\frac{d}{dt}u(t) = Bu(t)$

Splitting methods: Lie splitting

Iterate between the subproblems

$$\begin{aligned} \frac{d}{dt}v(t) &= Av(t), & t \in [0, \Delta t], & & \frac{d}{dt}w(t) &= Bw(t), & t \in [0, \Delta t], \\ v(0) &= \eta & & & w(0) &= v_1 \end{aligned}$$

$$\rightarrow v_1 \approx v(\Delta t)$$

$$\rightarrow w_1 \approx w(\Delta t)$$

$$\begin{aligned} \dot{u} &= Au + Bu \\ u_1 &= w_1 \approx u(\Delta t) \end{aligned}$$

Splitting methods: Lie splitting

Iterate between the subproblems

$$\begin{aligned} \frac{d}{dt}v(t) &= Av(t), & t \in [0, \Delta t], & & \frac{d}{dt}w(t) &= Bw(t), & t \in [0, \Delta t], \\ v(0) &= w_1 & & & w(0) &= v_2 \end{aligned}$$

$$\rightarrow v_2 \approx v(\Delta t)$$

$$\rightarrow w_2 \approx w(\Delta t)$$

$$\begin{aligned} \dot{u} &= Au + Bu \\ u_2 &= w_2 \approx u(2\Delta t) \end{aligned}$$

Splitting methods: Lie splitting

Iterate between the subproblems

$$\begin{aligned} \frac{d}{dt}v(t) &= Av(t), & t \in [0, \Delta t], & & \frac{d}{dt}w(t) &= Bw(t), & t \in [0, \Delta t], \\ v(0) &= w_{n-1} & & & w(0) &= v_n \end{aligned}$$

$$\rightarrow v_n \approx v(\Delta t)$$

$$\rightarrow w_n \approx w(\Delta t)$$

$$\begin{aligned} \dot{u} &= Au + Bu \\ u_n &= w_n \approx u(n\Delta t) = u(T) \end{aligned}$$

Splitting methods: convergence

For bounded operators A and B (think fixed spatial discretization),
Use Taylor expansion to prove convergence with order

$$\|u_n - u(n\Delta t)\| \leq C(\Delta t)^p$$

But $C \rightarrow \infty$ as discretization becomes finer !

Taylor expansion does not work for unbounded operators

Until recently: Only order theory for classical splitting methods
(i.e. for bounded operators)

In our group (Eskil Hansen)

Under certain conditions (linear maximal dissipative operators, etc.):

Order is preserved for classical splitting methods:

$$\|u_n - u(n\Delta t)\| \leq C(\Delta t)^p$$

C independent of spatial discretization mesh width!

IMEX Euler

$$\begin{aligned}\frac{d}{dt}u(t) &= Au(t) + Bu(t), \quad t \in [0, 1], \\ u(0) &= \eta\end{aligned}$$

A (non-linear) unbounded dissipative operator, like $\Delta(|u|^m u)$
 B Lipschitz continuous operator

Solve $\frac{d}{dt}u(t) = Au(t)$ by **Implicit** Euler

Solve $\frac{d}{dt}u(t) = Bu(t)$ by **Explicit** Euler

→ Same order as Implicit Euler for full problem (≤ 1)

(Eskil Hansen and Tony Stillfjord 2012)

Delay Differential Equations

Now trying to prove similar results for splitting DDEs, for example

$$\frac{d}{dt}u(t) = Au(t) + u(t-1), \quad t \in [0, 1],$$

$$u(0) = \eta$$

$$u(\tau) = f(\tau), \quad \tau \in [-1, 0]$$

Thank you